

Bayesian Quadrature for Multiple Related Integrals

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PN Conference

Collaborators



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Xi, X., Briol, F.-X., & Girolami, M. (2018). Bayesian Quadrature for Multiple Related Integrals. arXiv:1801.04153.

Bayesian Quadrature

- The goal of numerical integration is to find an approximation of the integral of some function $f : \mathcal{X} \rightarrow \mathbb{R}$ ($\mathbb{R}^p, p \in \mathbb{N}$) against some measure Π .
- This is often done use a quadrature/cubature rule:

$$\int_{\mathcal{X}} f(x) d\Pi(x) \approx \sum_{i=1}^n w_i f(x_i)$$

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What About Multiple Integrals?

- But what if we instead have a sequence of such functions f_1, f_2, \dots, f_D ? If we know something about how f_1 relates to f_2 (etc...) then we might be able to use that information in the design of a numerical integration method.
- It might make more sense to approximate the integral with a quadrature rule of the form:

$$\hat{\Pi}[f_d] = \sum_{d'=1}^D \sum_{i=1}^N (\mathbf{w}_i)_{dd'} f_{d'}(x_{d'i}).$$

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Bayesian Quadrature for Multiple Related Functions

- We can use the same type of results for Gaussian Processes on the extended space of vector-valued functions $\mathbf{f} : \mathcal{X} \rightarrow \mathbb{R}^D$ (rather than $f : \mathcal{X} \rightarrow \mathbb{R}$) where $\mathbf{f}(x) = (f_1(x), \dots, f_D(x))$.
- This approach allow us to directly encode the relation between each function f_i by specifying the kernel K .
- In this case the posterior distribution is a $\mathcal{GP}(\mathbf{m}_n, \mathbf{K}_n)$ with vector-valued mean $\mathbf{m}_n : \mathcal{X} \rightarrow \mathbb{R}^D$ and matrix-valued covariance $\mathbf{K}_n : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}^{D \times D}$:

$$\begin{aligned}\mathbf{m}_n(\mathbf{x}) &= \mathbf{K}(\mathbf{x}, \mathbf{X})\mathbf{K}(\mathbf{X}, \mathbf{X})^{-1}\mathbf{f}(\mathbf{X}) \\ \mathbf{K}_n(\mathbf{x}, \mathbf{x}') &= \mathbf{K}(\mathbf{x}, \mathbf{x}') - \mathbf{K}(\mathbf{x}, \mathbf{X})\mathbf{K}(\mathbf{X}, \mathbf{X})^{-1}\mathbf{K}(\mathbf{X}, \mathbf{x}').\end{aligned}$$

The overall cost for computing this is $\mathcal{O}(n^3 D^3)$.

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The overall cost for computing this is $\mathcal{O}(n^3 D^3)$.

- Consider multi-output Bayesian Quadrature with a $\mathcal{GP}(\mathbf{0}, \mathbf{K})$ prior on $\mathbf{f} = (f_1, \dots, f_D)^\top$. The posterior distribution on $\Pi[\mathbf{f}]$ is a D -dimensional Gaussian with mean and covariance matrix:

$$\begin{aligned}\mathbb{E}_N [\Pi[\mathbf{f}]] &= \Pi[\mathbf{K}(\cdot, \mathbf{X})]\mathbf{K}(\mathbf{X}, \mathbf{X})^{-1}\mathbf{f}(\mathbf{X}) \\ \mathbb{V}_N [\Pi[\mathbf{f}]] &= \Pi\bar{\Pi}[\mathbf{K}] - \Pi[\mathbf{K}(\cdot, \mathbf{X})]\mathbf{K}(\mathbf{X}, \mathbf{X})^{-1}\bar{\Pi}[\mathbf{K}(\mathbf{X}, \cdot)]\end{aligned}$$

- Kernel evaluations are now matrix-valued (i.e. in $\mathbb{R}^{D \times D}$) as opposed to scalar-valued. A simple example is the following separable kernel:

$$\mathbf{K}(x, x') = \mathbf{B}k(x, x')$$

\mathbf{B} encodes the covariance between function, and k the type of function in each of the components.

- This reduces the cost to $\mathcal{O}(n^3 + D^3)$. We also can show that the convergence rate will be the same as for the uni-output BQ rule based on k (and we can extend the theory to the misspecified setting).

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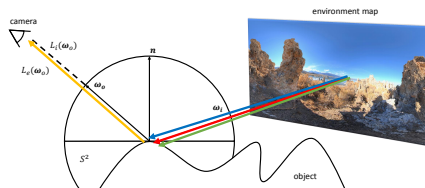
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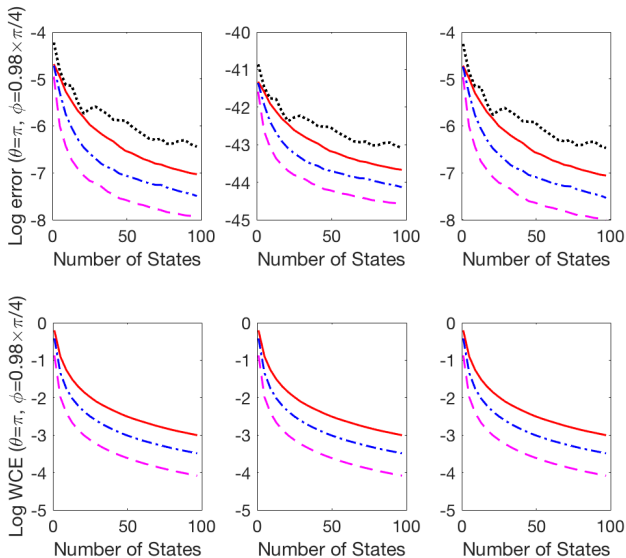
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Multi-output BQ for Global Illumination



- We compute integrals for different integrands based on various angles ω_0 (akin to a camera moving).
- We pick a separable kernel $\mathbf{K}(x, x') = \mathbf{B}k(x, x')$ where \mathbf{B} is chosen to represent the angle between integrands and $k(\mathbf{x}, \mathbf{x}') = \frac{8}{3} - \|\mathbf{x} - \mathbf{x}'\|_2$.
- We can prove that the worst-case integration error converges at a rate $\mathcal{O}(n^{-\frac{3}{4}})$ for each integrand. This is the same rate as uni-output BQ (but we usually improve on constants).

Multi-output BQ for the Computer Graphics Example



The Broader Picture

Short summary: The multi-output Bayesian Quadrature algorithm is an example of how joint-models can lead to significant improvements in performance.

Interesting Question: Can this idea, known as transfer learning in the ML literature, be useful in other areas of probabilistic numerics?

Minor Question: Does anyone know of any other literature on the topic of integrating multiple related functions?

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